

**In the Specification:**

In paragraph 0001 of published patent application no. 2001-0038160:

A method and a device for manufacturing a flexible strip of at least two different masses flowable with the addition of heat. The invention relates to a method and a device for manufacturing a flexible strip of at least two different masses flowable with the addition of heat; ~~according to the preamble of claim 1 and claim 7.~~ The manufacture of such strips with the help of a strip casting device in a continuous method is, for example, a method step with the manufacture of soft gelatine capsules. By way of the use of differently colored gelatine masses, it is possible at the same time to achieve a certain pattern on the capsule casing.

Between paragraphs 0001 and 0002 of published patent application no. 2001-0038160, please insert:

**BACKGROUND OF THE INVENTION**

Between paragraphs 0003 and 0004 of published patent application no. 2001-0038160, please insert:

**BRIEF SUMMARY OF THE INVENTION**

In paragraph 0004 of published patent application no. 2001-0038160:

It is therefore the object of the invention to provide a method of the previously mentioned type with which, with simple design means, as homogeneous as possible patterned strip may be

manufactured, wherein also complicated patterns may be realised. The device is to be as simple as possible in its handling and maintenance. ~~This object is achieved with respect to the method by way of a method with the features of claim 1, and with respect to the device by way of a device with the features of claim 7.~~

Between paragraphs 0016 and 0017 of published patent application no. 2001-0038160, please insert:

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

Between paragraphs 0021 and 0022 of published patent application no. 2001-0038160, please insert:

DETAILED DESCRIPTION OF THE INVENTION

In paragraph 0026 of published patent application no. 2001-0038160:

At a distance to the fixed sidewall 17 the supply tubes are held in a manipulator 20 and here are likewise guided in joint bearings 19. The two rows 21 and 22 of injection nozzles may at the same time be held in separate manipulators, it would even be conceivable for each injection nozzle to be individually manipulated. As is indicated in FIG. 3, the manipulator 20 may move the supply tubes 24 and thus the individual injection nozzles 21, 22 in various spacial axes 26. The manipulator could at the same time be connected to a programmable computer, which controls the individual movement sequences.